Almost Ten Years of Process Algebras and Model Checking for Multiprocessor Architectures Hubert Garavel

joint work with many other persons at BULL and INRIA

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Formal methods for hardware design

- Characteristics of hardware circuits:
 - increasingly complex
 - shortened design cycles
 - errors are expensive
 - fundry costs
 - no patches
- Hardware designers are:
 - open to formal methods and verification
 - but used to synchronous, deterministic systems



In this talk

- Almost 10 years of BULL-INRIA collaboration
- On the Bull side
 - Asynchronous issues in multiprocessor architectures
 - Bus arbitration protocols
 - Cache coherency protocols
- On the INRIA/VASY side
 - Process algebra and model checking
 - LOTOS specification language (ISO 8807)
 - CADP toolbox (Construction and Analysis of Distributed Processes)



The CADP toolbox http://www.inrialpes.fr/vasy/cadp

- Main features:
 - LOTOS -> C compilers
 - equivalence checking (bisimulations)
 - model checking (modal mu-calculus)
 - visual checking (graph drawing)
 - exhaustive, partial, on the fly, compositional verification
 - step by step simulation, random execution
 - C code generation, rapid prototyping
 - test case generation
- Wide dissemination:
 - license agreement signed with 310 organizations
 - installed on 840 machines in 2003
 - 72 case studies done with CADP
 - 16 research tools connected to CADP
 - 17 academic courses using CADP



Phase 1 (1995–1996)



Target: Powerscale

- Multiprocessor architecture
- based on PowerPC microprocessors
- used in Bull's Escala servers and workstations
- With a hidden bug





Formal specification



- 720 lines of LOTOS
- 7 concurrent processes:
 - processors
 - memory controller
 - bus arbiter



Verification results

- Four correctness properties identified:
 - Proper response to bus requests
 - Fairness of the arbitration
 - Order of grants for address-data requests
 - Correctness of the DBG flow control
- State enumeration would fail (potentially 10^12 states)
- Compositional verification (bisimulations) was used
- Using CADP, the bug could be found in a few minutes

FORTE'96 paper [Chehaibar-Garavel-Mounier-Tawbi-Zulian-96]



Phase 2 (1996–Sep. 1998)



Target: Polykid

- A multiprocessor architecture under design at Bull Italy
- based on PowerPC processors
- CC-NUMA memory model



Specification and verification

- Several specifications developed
 - Polykid architecture: 4,000 lines of LOTOS
 - Cache coherency rules: 2,000 lines of LOTOS
- Validation by simulation and model checking on abstracted subsets (2,000 lines of LOTOS, 10 concurrent processes)
- Several problems (deadlocks, memory consistency violation, undocumented behaviours) found:
 - phase 1: 55 questions
 - phase 2: 20 questions, 7 serious issues
 - phase 3: 13 serious issues



Test generation using TGV



- 75 tests generated (more than 400 states each) in 1 man.month
- Tools developed for automated test execution
- Test execution requires less than 20 hours
- 5 new bugs discovered in VHDL design
- IWTCS'98 paper: [Kahlouche-Viho-Zendri-98]



The actual Polykid testbench





Hardware emulation using EXEC/CAESAR



- Replacement of a missing ASIC by a software emulation running on a PowerPC microprocessor
- Target: RCC (*Remote Cache Controller*)
- 3,400 lines of LOTOS, 7,000 lines of C
- Exec/Caesar: <u>The</u> correct scheme to interface process algebra specs with a real environment



The end of Polykid: A sad story...

- Polykid was too late on market
- Eventually, Bull cancelled the Polykid project
- Bull's Italian plant was closed

But:

- Formal methods had proven to be valuable
- BULL-INRIA collaboration would continue with a new architecture

STTT paper in 2001: [Garavel-Viho-Zendri-01]



Intermezzo (1998–2002)

joint work with Holger Hermanns



Target: SCSI-2 bus arbitration protocol

- SCSI-2: a former IEEE computer bus standard
- Bus grant based on fixed priorities (SCSI numbers)



Unexpected OS deadlocks reported by Bull



Specification and verification

• SCSI-2 bus arbiter: only 220 lines of LOTOS The n-party rendezvous of LOTOS with its value negociation features is unavoidable for concise modeling (a challenge for other formalisms!)

 Compositional state space generation and model checking using CADP The starvation problem was confirmed (This problem was fixed in SCSI-3 standard)



Performance evaluation

• Application of H. Hermanns' PhD thesis: Performance models can be obtained by limited changes in a LOTOS specification

 Compositional generation of Markov chains using CADP
 Steady state analysis suggests strategies to avoid starvation and increase throughput

• FME'02 paper [Garavel-Hermanns-02]



Phase 3 (Sep. 1998-now)



The FormalFame Team



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Target: Bull's NovaScale servers





- 64-bit high-end servers
- based on Intel's Itanium-2
- CC-NUMA architecture: "FAME"
- Windows, Linux, GCOS 7 and 8





FAME (Flexible Architecture for Multiple Environments)







Focus on most critical, asynchronous parts

- Chipset components for an early prototype of FAME based on Itanium-1 ("Merced") processors:
 - CCS (Core Chip Set)
 - NCS (Network Chip Set)
- B-SPS / FSS (Fame Scalability Switch)
 - core of the FAME architecture
 - implements message routing and cache coherency protocol
 - contains several "units", which themselves contain "blocks"



Formal specification activities

- CCS (*Core Chip Set*) 1,200 lines of LOTOS, 10 concurrent processes
- NCS (*Network Chip Set*) 1,200 lines of LOTOS, 16 concurrent processes
- B-SPS/FSS (*Fame Scalability Switch*) 5,000 lines of LOTOS, 12 concurrent processes 4,500 lines of LOTOS, 7 concurrent processes
- ILU (Interleaving Unit) 8,900 lines of LOTOS, 3,400 lines of C
- PRR (Pending Requests Response) 7,500 lines of LOTOS, 200 lines of C



Formal specification results

- All the LOTOS code was written by Bull
- Several design levels addressed:
 - system-level: CCS, NCS, B-SPS/FSS
 - unit-level: ILU
 - block-level: PRR
- Various issues detected, e.g., in the cache coherence protocol
 - In 2000: 10 issues raised
 - In 2001: 2 ambiguities pointed out



Directed test generation using TGV



- Tests produced for CCS:
 - 21 base tests (1 mn/test)
 - 50 collision tests (15 mn/test)
 - 1 generalized test (1 day)
- Tests produced for NCS:
 - 50 base tests (30 sec/test)



test platform

Random test generation using Executor



Assumptions:

- PRR is deterministic (same inputs => same outputs)
- randomness introduced in C implementation of LOTOS types
 Results:
- Generation of large sequences (100,000 transactions)
- Detection of a non-conformity between the LOTOS and Verilog codes for PRR v1 (not detected otherwise)





- Various coverage criteria (Petri net transitions, LOTOS visible labels and their offers)
- Combination of random and directed approaches
 - Random firing of tau transitions
 - History-based guidance to maximize coverage



Trace validation: Former approach



- Goal:
 - find bugs in VCD traces
 - measure coverage of test effort
- Traces are large (> 10,000 bus transactions)
- Traces are complex (nested transactions)
- Writing a dedicated "Verifier" is costly (and it may contain errors)



Trace validation: Formal approaches



- Principle: reuse the LOTOS spec. to check traces
 - BISIMULATOR: trace inclusion
 - EXHIBITOR: regular expression matching
 - EVALUATOR: temporal formula satisfaction
- What about coverage?





Principles:

- Temporal formulas generated from state/transitions tables
- "Markers" indicate if a formula is "activated" by a given trace
- Formula activated by no trace => more traces needed to cover the test plan
- This measures "functional coverage" (wrt B-SPS specification) — different from "structural coverage" (wrt Verilog design) not done before by Bull
- SPIN'04 paper on SEQ.OPEN [Garavel-Mateescu-04]



Trace validation with coverage

Main results:

- In 2000: major bug found: ambiguity of informal spec. (also found by "Verifier")
- Collision traces: 130 Mbytes of traces analyzed (about 24,000 transactions): no issue detected
- Interface traces: 761 properties verified, 216 not covered (in fact, 24) => 2 missing tests added in 2001
- Directory traces: 518 properties verified, 196 not covered
 => 1 missing test added in 2001
- The approach is used at every B-SPS revision (official part of Bull's design methodology)
- Performance: 7.4 millions of model checking jobs done in 23 hours on a standard PC (Pentium III 700 MHz, 1 Gbyte RAM)



Conclusion



Summary

- A long standing research-industry collaboration
- Four different case-studies tackled
- Three different design levels addressed:
 - System (bus arbiters, cache coherency protocols)
 - Unit (ILU)
 - Block (PRR)
- Many functionalities supported:
 - Formal specification
 - Simulation, random execution
 - Hardware emulation, co-simulation
 - Test generation, execution, and coverage
 - Model checking verification
 - Performance evaluation



Conclusions

- The approach is integrated in Bull's industrial process
- Main lessons:
 - LOTOS is usable by architects and verification engineers
 - CADP tools are robust enough (with some maintenance)
 - "High quality" errors have been detected
 - Components developed with LOTOS are more reliable
 - Test effort is better focused on difficult parts
- Future work:
 - Comparative benchmarks with industrial PSL tools
 - Application to asynchronous circuits (VASY + CEA/LETI)



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