A Comparison of Two SystemC/TLM Semantics for Formal Verification

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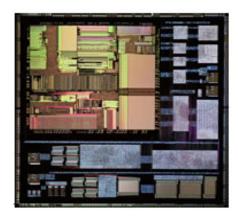
Outline

- > Transaction level modeling in SystemC
- Verifying SystemC/TLM
- The Lotos/CADP framework for semantics comparison
- Conclusion



Electronic design models

Physical chip

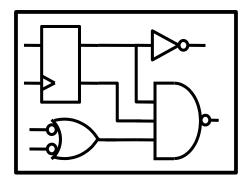


- Accurate
- Fast

but:

- Too late
- Hard to debug

Hardware description (RTL)



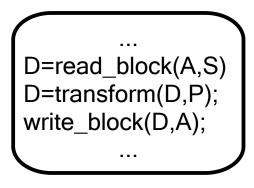
- Accurate
- Easy to debug

but:

- Too late
- Very slow



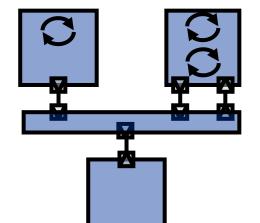
Abstract model (TLM)



- Fast
- Early available but:
 - Less accurate
 - No synthesis

Untimed transaction level models

- Embedded software programmer's view
 - Architecture: modules
 - Behavior: processes
 - Communication:
 - Transactions (inter-modules)
 - Synchronizations (inter-processes)
- > Untimed TLM model of computation
 - Concurrent execution of independent processes
 - System synchronization for causal dependencies
- Reference model
 - Functional verification
 - Embedded software development
 - Co-simulation





SystemC

- ► A C++ library
- >Heterogeneous (hard/soft) system modeling
 - Module and port classes to describe architectures
 - Threads and events to describe behaviors
- > System simulation
 - A global nonpreemptive scheduler
 - A simulated time



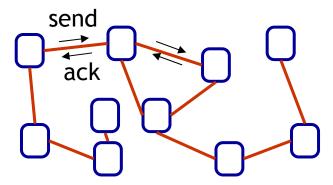
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Verifying SystemC/TLM models

- Main TLM modeling challenge: find all the synchronizations needed between processes
 - Not the software sequential algorithms
 - But the interactions between components

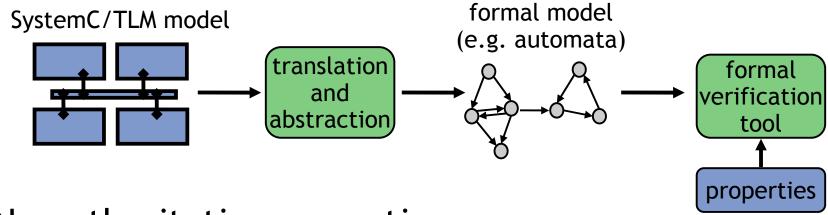


- Verification needs to explore
 - Data space and
 - Processes interleaving space



Semantics of SystemC/TLM

> Usual approach for formal verification



- No authoritative semantics
 - SystemC simulation semantics
 - Concurrent TLM semantics



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A uniform framework for comparison

Lotos

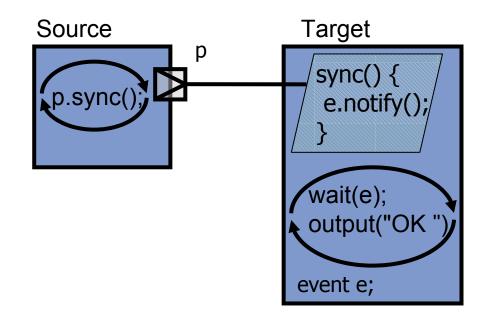
- Process algebra
- Formal semantics
 - Asynchronous concurrent processes
 - Synchronization and communication by *rendezvous*

CADP

- µ-calculus model-checking
- Equivalence checking
- Compositional verification



Motivating example 1

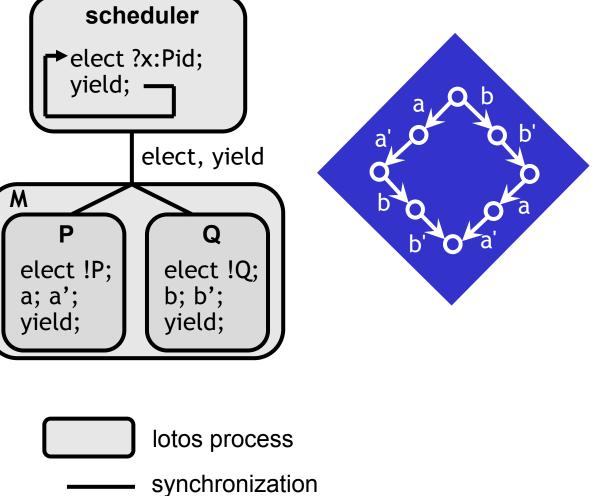


Incomplete synchronization between Source and Target processes: possible system deadlock

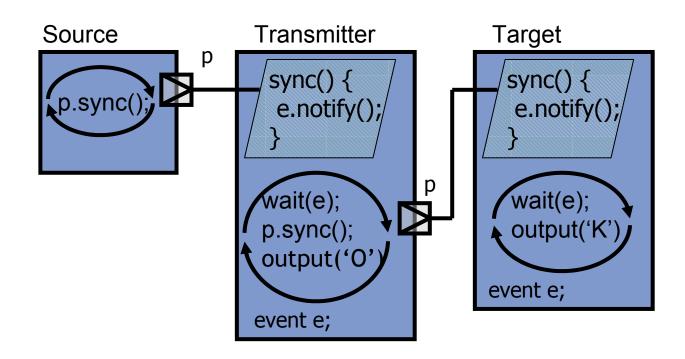


SystemC simulation semantics in Lotos

```
SC_MODULE(M) {
    SC_HAS_PROCESS(M);
    SC_CTOR(M) {
        SC_THREAD(P);
        SC_THREAD(Q);
    }
    void P() { a; a' }
    void Q() { b; b' }
};
```



Motivating example 2

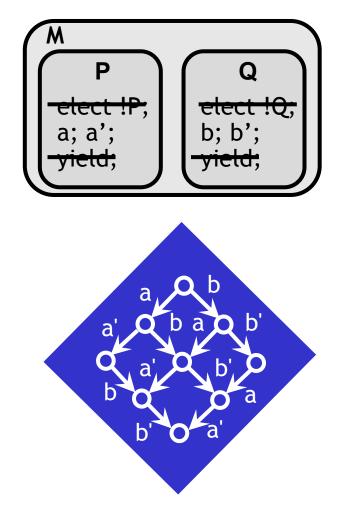


- In a concurrent implementation, "OK" and "KO" are both possible outputs
- With SystemC simulation semantics, the possibly erroneous "KO" output is missed



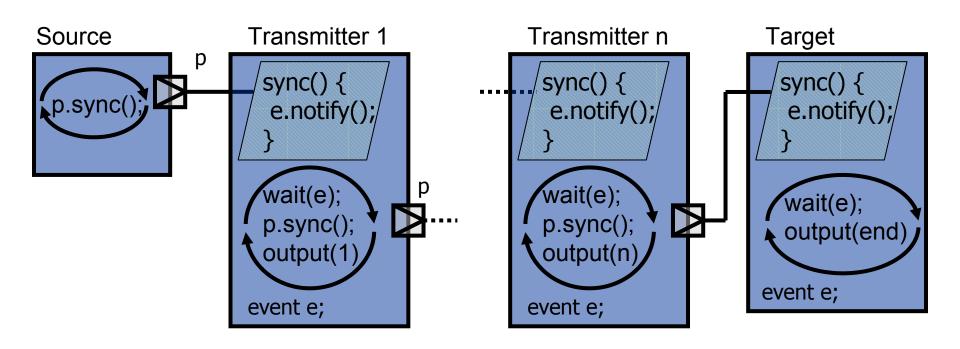
Concurrent TLM semantics in Lotos

```
SC_MODULE(M) {
    SC_HAS_PROCESS(M);
    SC_CTOR(M) {
        SC_THREAD(P);
        SC_THREAD(Q);
    }
    void P() { a; a' }
    void Q() { b; b' }
};
```





Comparison benchmark





Comparison of the two semantics

Qualitative

- Concurrent TLM ⊃_{branching} SystemC simulation
- Concurrent TLM ⊄_{branching} SystemC simulation
- The concurrent TLM semantics generalizes the SystemC simulation semantics

Quantitative

- SystemC simulation generates bigger LTSs although they are strictly included in concurrent TLM models
- Once minimized, interesting behaviors are indeed less numerous in SystemC simulation models



Conclusion

- Existing SystemC/TLM formal semantics are difficult to compare
- > We used Lotos/CADP as a uniform framework to
 - Show concurrent TLM semantics generalizes SystemC simulation semantics
 - Show concurrent TLM semantics scales as well as SystemC simulation semantics
 - Evaluate the performance impact of several transaction encoding variants



Perspectives

- > On-going work on an industrial case-study (approx.
 26 000 lines of code)
- > Automating the translation
- Inverse translation: Lotos into SystemC/TLM



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